

### Urban Sustainability R&D Symposia 2021- Built Environment

Interoperability of Robotics & Automation in Built Environment

10/18/202

24<sup>th</sup> September, 2021





### Agenda

Company Overview

□ Challenges facing Built Environment vs Healthcare

□ Features of SMART Hospitals

□ Interoperability use-case in Healthcare

□ Future of On-site construction

□ Interoperability Concept for Built Environment

Benefits to Built Environment







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### **Company Overview**





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### **Challenges facing Built Environment**

#### BE faces similar challenges to Healthcare



- Heavy dependence on labour
- Inconsistent quality due to delays due to multiple vendors and parties with different capabilities and maturity
- Complex manual processes which are not easy to automate
- Safety of workers is paramount
- Unstructured, dynamic environments involving humans, equipment, robots and automation solutions
- Legacy IT systems



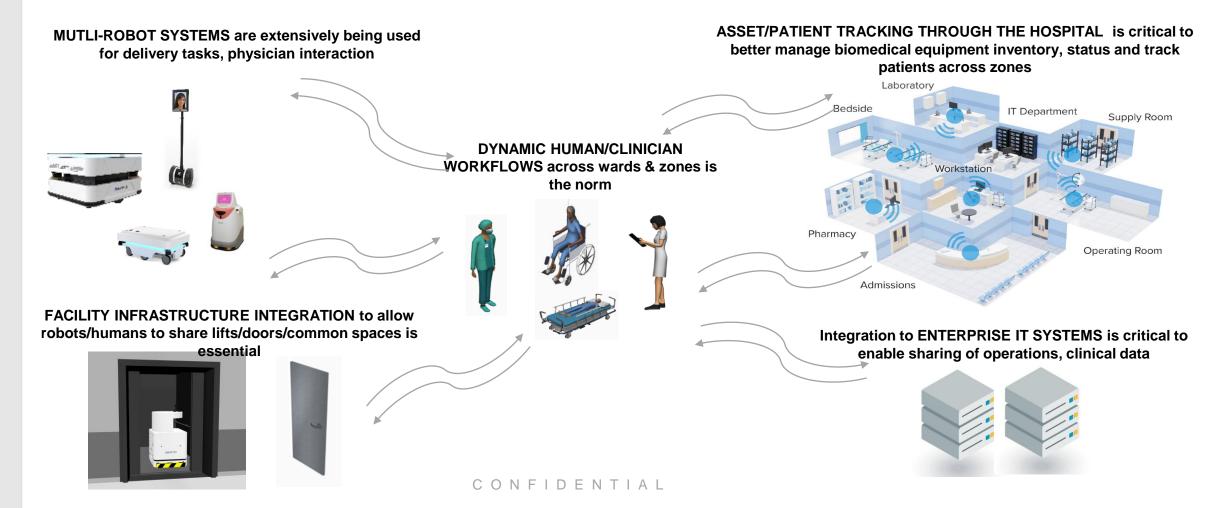
- Heavy dependence on nurses, porters and operational staff
- Multiple vendors for devices, IT solutions, infrastructure
- Complex manual processes which are not easy to automate
- Dynamic environment with movement of humans, beds, wheelchairs, robots
- Safety of nurses/healthcare workers is always a critical consideration
- Legacy IT systems

### Why does Interoperability Matter?

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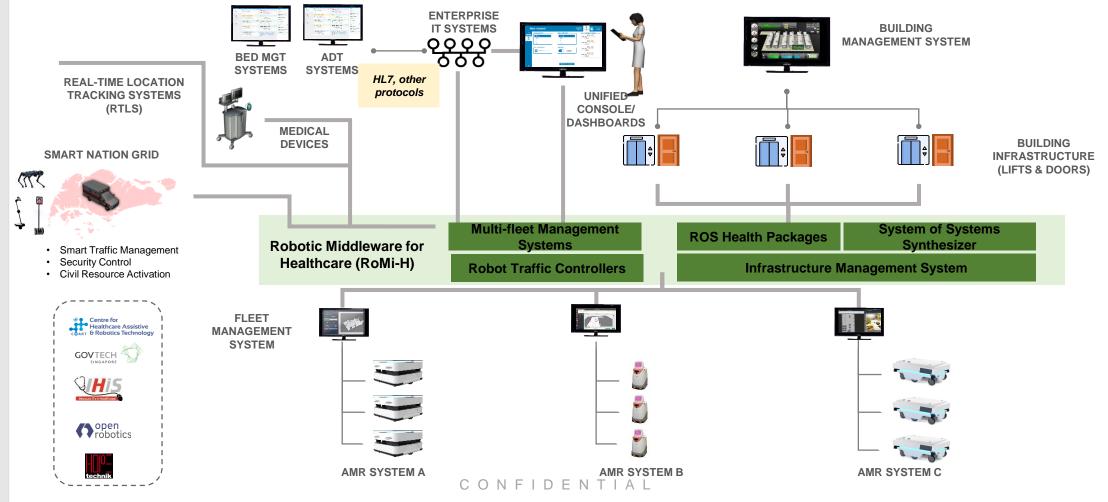
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SMART Hospitals will require process flow automations where multi-robot/multi vendor systems work seamlessly with humans, other automation systems and facility infrastructure



# Interoperability concept from Healthcare: The foundation to scale robotics & automation

RoMi-H: Interoperability layer that enables high performance hospitals through intrahospital logistics using robotics, asset/patient tracking and efficient resource management



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### **Future of On-site Construction**

Robotics & automation will become a feature of BE – especially on-site construction & Facilities Management for use-cases like safe & intuitive tele-operation, material handling, inspection/surveillance, asset/human tracking and safety uddates to Project Managers



Robots for Drywall finishing



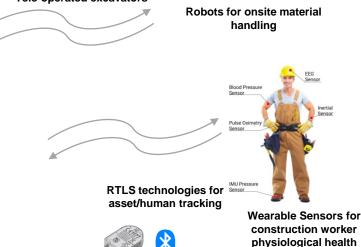
UAVs for surveying, communication & management

Tele-operated cranes with higher load capacity



VR for on-site construction activities

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tracking



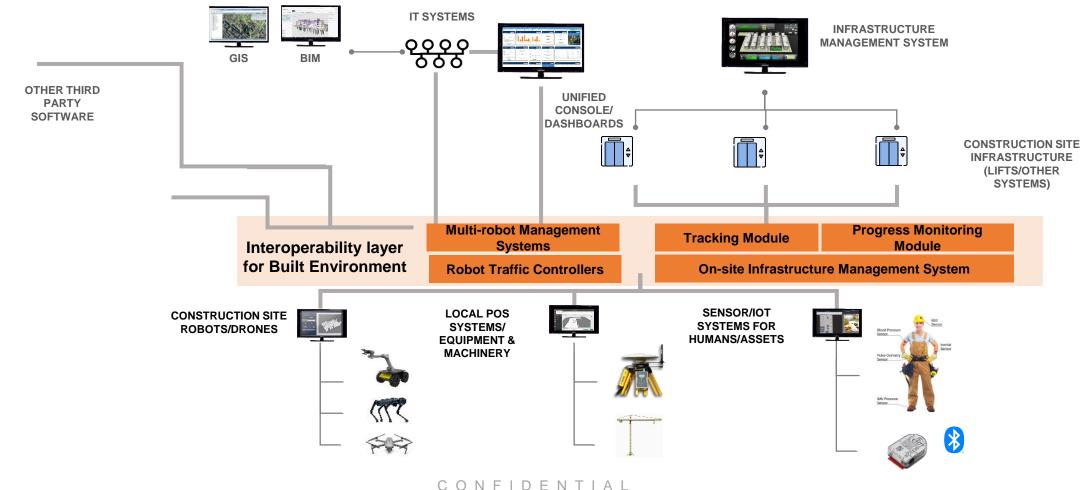
### Interoperability Concept for Built Environment

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We envision the creation of a library of tools and plugins that enables interoperability of robotic assets, on-site equipment, sensors, BIM, GIS tools used in onsite construction





### **Benefits to Built Environment**

The interoperability layer can become the standard baseline infrastructure for all on-site construction solutions

#### **Optimization**



Ability to interoperate robot assets with other equipment, software will improve utilization and help planning

#### Visibility



Construction project managers/operators have better visibility on assets /resources and can plan better

#### **Cost Savings**



Reduce cost of onsite systems integration due to the presence of several standardized plug-ins and common library of tools

#### **Scalability**



The interoperability platform allows scalability across a range of robotics, sensor and automation platforms

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## Q&A



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